

The Orbital Motion of The Martian Satellites:  
An Application of Artificial Satellite '1' Theory

by

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The Martian satellites, Phobos and Deimos, were discovered in 1877 by Asaph Hall. They move in close, nearly circular orbits slightly inclined to the Martian equator. Their principal orbital perturbations are due to the non-spherical nature of the Martian gravity field, but they are also significantly affected by solar perturbations. Planetary perturbations, however, are negligible, and because of their small masses, their mutual perturbations are negligible as well. The studies of their motions from observations have found evidence of a secular acceleration in Phobos' orbit. A similar acceleration in Deimos' orbit is suggested but much less certain. Sharpless (1945) determined such a large value for Phobos' acceleration that it implied an impact with Mars within a few tens of millions of years. One explanation for the source of that acceleration (atmospheric drag on hollow bodies) led to the speculation that the Martian satellites were in fact artificial bodies (Shklovskii and Sagan, 1966). Perhaps it is therefore appropriate to consider employing artificial satellite theory to describe their orbits.

Since their discovery a number of theories have been developed to represent the satellites' orbital motions. These early theories were primarily kinematical in nature, however, Sinclair (1972) created a dynamical theory. Sinclair's work was inspired by the artificial satellite theory of Brouwer (1959) although his variation of parameters approach more closely matched Kozai's (1959, 1962) approach rather than that of Brouwer who favored the von Zeipel technique. Artificial satellite theory has the Earth's (planet's) equator as its reference plane. However, when the Martian equator is used with the Martian satellites, large periodic perturbations due to the Sun appear in the inclinations and nodes, especially for Deimos. Sinclair found that by modifying the theory and referring the elements to the Laplacian planes (Laplace, 1805; Dobrovolskis, 1993), those perturbations could be avoided. The satellite orbits precess almost uniformly on the Laplacian planes because the latter are defined such that the periodic perturbations due to the Martian oblateness and Sun just cancel each other. Included in the theory is a secular acceleration term in the satellites' longitudes to account for any change in the satellites' mean motions. The small observed acceleration for Phobos is currently attributed to the gravitational attraction of the tidal bulge raised by it, on Mars. No statistically significant acceleration has yet been observed for Deimos. Sinclair later expanded his theory (Sinclair, 1989) to include a few more terms, especially a previously overlooked long period longitude term pointed out by Born and Duxbury (1975). This term has a 115 km amplitude for Deimos and is an order of magnitude greater than the next largest periodic perturbation. The theory at this point was estimated to have an accuracy better than 500 m for Phobos and 1 km for Deimos based on a comparison with numerical integration over 4000 days.

Morley (1990) extended Sinclair's work by increasing the accuracy of the terms describing the secular and periodic perturbations and by adding perturbations due to the tesseral harmonics of the Mars gravity field, short period solar perturbations, and a number of smaller terms. He also extended the theory to second order in the longitude. From a comparison with a 60 day numerical integration, he estimated the theory to be accurate to better than 100 m for both satellites.

We have adopted the Sinclair-Morley theory as the basis for Martian satellite ephemerides to be developed in support of JPL's Mars Exploration Program. The theory's accuracy is more than sufficient for currently projected spacecraft operations needs. Moreover, its fully analytical nature permits modifications and updates in light of future observations and improvements in the Martian gravity field parameters. As part of the initial verification of theory, we compared our implementation to a 60 day numerical integration and found, as did Morley, an accuracy better than 100 meters. We then extended the comparison to 20 years (7300 days) for Phobos and 80 years (29,220 days) for Deimos. The former comparison covered a time span about 1.8 times the longest period in the Phobos theory, and the latter covered about 1.5 times the longest period in Deimos theory. The long period comparison suggested that the theories were good to only 300 meters for Phobos and 900 meters for Deimos. Although these accuracies are still adequate for our current purposes, we made an attempt to recover the 100 meter accuracy by modifying the theory. The changes included: (1) basing the Laplacian planes in mean distance from Mars rather than on the semi-major axis; (2) modifying the computation of the secular perturbations to use the semilatus rectum instead of semi-major axis and eccentricity; (3) replacing the  $J_2^2$  secular perturbation with that of Kinoshita (1977); (4) adding the  $J_3^2/J_2$ ,  $J_2^3$ , and  $J_2J_4$  secular perturbations from Kinoshita (1977); (5) adding the  $J_5$  and  $J_7$  periodic perturbations from Brouwer (1959); (6) incorporating additional terms in the  $J_{22}$  periodic perturbations (Guinn, 1991); (7) replacing the original long period mean longitude perturbation due to  $J_2$  and the Sun with a more precise expression; (8) adding additional long period solar perturbation terms. After the changes the Phobos accuracy improved to about 120 meters, close to our goal. However, the Deimos accuracy improved to only about 500 meters. It is limited by a long period mean longitude effect, the source of which is currently unknown, and by insufficient accuracy in the determination of the Laplacian plane inclination.

This paper describes our extended Sinclair-Morley theory for the Martian satellites. It outlines the original theory, presents the modifications and additional terms, and compares the theory with numerical integration. The latter comparisons include an examination of the effects of neglected terms in the theory. We also provide a comparison with one of the other competing dynamical Martian satellite theories, namely the MASPHO/ESADE theory (Chapront-Touzé, 1988, 1990a, 1990b). Finally we discuss the limitations of the theory in the context of its use to support JPL's Mars Exploration Program.

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